Figure 2 shows a computer-calculated plot of log J\* against the Stokes number St for poorly conducting particles in the case of potential flow past a sphere of radius R. Curves 1-3 correspond to Re = 10,  $10^2$ , and  $10^3$ . When St =  $\infty$  we have

$$J^* = 2 \int_0^1 (\sqrt[4]{1-b^{*2}})^{7/10} b^* db^* = \frac{20}{27}.$$

Figures 1 and 2 indicate that there is a critical value of the Stokes number  $(St_0 > 0)$ , at which  $J^*$  becomes zero. When the Stokes number is less than  $St_0$  the particles do not reach the body surface. In this case  $J^* \equiv 0$  and there is no electrification of the body.

As an example we consider the electrification of a spherical body of diameter 2R = 10 m in an aerosol flow of ice particles with diameter  $a = 10^{-4}$  m, concentration  $\eta^0 = 10^8$  m<sup>-3</sup>, and flow velocity  $u^0 = 100$  m/sec. For pure ice  $\varepsilon_p = 72$ ,  $\sigma_p = 4 \cdot 10^{-7} \ \Omega^{-1} \cdot m^{-1}$ ,  $e = 1.6 \cdot 10^{-19}$ C,  $n_0 \simeq 10^{19} - 10^{20}$  m<sup>-3</sup>,  $E_p^Y = 3 \cdot 10^9$  N/m<sup>2</sup>,  $\nu_p = 0.3$ . In this case the inequality  $\tau \neq 10^{-6}$  sec  $\ll \tau_e = 1.6 \cdot 10^{-3}$  sec is fulfilled and the theory expounded in Paragraph 4 is applicable. For these numerical values of the parameters we have St = 2, Re =  $10^3$ ,  $J^* = 10^{-1}$ ,  $\Delta e_p^0 = -5 \cdot 10^{-16}$  C,  $J/S_M = 5 \cdot 10^{-7}$  A/m<sup>2</sup>. Such current densities are actually observed when bodies move in clouds and precipitation [2].

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## APPLICATION OF THE MULTIPLE-SCALE METHOD IN THE PROBLEM OF WAVES ON THE SURFACE OF A LIQUID

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Sretenskii [1] has used the method of integral transforms to solve the problem of waves on the surface of a viscous incompressible liquid of inifinite depth. In the low-viscosity case Potetyunko and Strubshchik [2] have constructed asymptotic expansions that are valid in finite time intervals.

In this article we consider the planar Cauchy-Poisson problem for the linearized Navier-Stokes equations in application to the motion of an incompressible low-viscosity liquid under the action of an initial elevation of the free surface:

$$\partial \mathbf{v}/\partial t = -\nabla p + \varepsilon^2 \Delta \mathbf{v}, \text{ div } \mathbf{v} = 0,$$
  

$$p = p_r + \lambda z, \mathbf{v} = 0, \zeta = \zeta_* (x) (t = 0), -p + \lambda \zeta + 2\varepsilon^2 \partial v_z/\partial z = 0 (z = 0),$$
  

$$\partial \zeta/\partial t = v_z, \partial v_x/\partial z + \partial v_z/\partial x = 0 (z = 0),$$
  

$$(\mathbf{v}, \partial \mathbf{v}/\partial x, p, \partial p/\partial x, \zeta_*) \rightarrow 0, |x| \rightarrow \infty,$$
  

$$\mathbf{v} = 0 \qquad (z = -H).$$
(1)

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All quantities in (1) are dimensionless. Here  $\varepsilon^2 = 1/\text{Re}$  is a small parameter; Re, Reynolds number;  $p_r$ , hydrodynamic pressure;  $\zeta(x, t)$  describes the elevation profile of the free boundary;  $\lambda = \text{gT}^2 \alpha^{-1}$ ; g, acceleration of gravity; and  $\alpha$ , T, units of length and time. The coordinate origin is placed on the undisturbed surface. The z axis is directed vertically upward. The liquid is set in motion by the initial elevation of the free boundary  $\zeta_*(x)$ .

We construct asymptotic expansions of the solution of problem (1) as  $\varepsilon \rightarrow 0$  in the form

$$\mathbf{v} \sim \sum_{k=0}^{N} \varepsilon^{k} (\mathbf{v}_{k} + \mathbf{w}_{k} + \mathbf{h}_{k}), \, \zeta \sim \sum_{k=0}^{N} \varepsilon^{k} \zeta_{k}.$$
<sup>(2)</sup>

An analogous series is constructed for the function p with coefficients  $p_k$ ,  $r_k$ ,  $q_k$ . In the case of vanishing viscosity, boundary layers are formed near the boundaries of the domain. We denote by  $D_S$  and  $D_{\Gamma}$  the domains of the boundary layers near the solid boundary S and the free surface  $\Gamma$ . Then  $w_k$  and  $r_k$  are functions of the nature of solutions of the boundary-layer problem in  $D_S$ , while  $h_k$  and  $q_k$  are the same in  $D_{\Gamma}$ .

The functions  $\mathbf{v}_k$  and  $\mathbf{p}_k$ , which characterize the flow everywhere outside  $\mathbf{D}_S$  and  $\mathbf{D}_{\Gamma}$ , are found by the first iteration process of [3] and are expressed in terms of the scalar function  $\varphi_k(\mathbf{x}, \mathbf{z}, \mathbf{t})$  according to the formulas  $\mathbf{v}_k = \operatorname{grad} \varphi_k$ ,  $\mathbf{p}_k = -\partial \varphi_k / \partial \mathbf{t}$ , where  $\varphi_k$  satisfies the Laplace equation  $\Delta \varphi_k = 0$ . We introduce the Fourier transform with respect to the coordinate x and the Laplace transform with respect to the time t:

$$\Phi_f(\xi, z, t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{i\xi x} f(x, z, t) dx, Lf = \sigma \int_{0}^{\infty} f e^{-\sigma t} dt,$$

and we specify two time scales  $t_1$  and  $\tau$  [4]:

$$t_{1} = t + \sum_{k=0}^{N} \varepsilon^{k} \beta_{k}(t, \xi), \ \tau = \sum_{k=1}^{N} \varepsilon^{k} \omega_{k}(t, \xi).$$
(3)

The principal terms of the asymptotic representation (2)  $\mathbf{v}_0$ ,  $\mathbf{p}_0$ ,  $\boldsymbol{\zeta}_0$  are determined from the solution of the corresponding ideal-fluid flow problem [3], and the coefficient  $\boldsymbol{\zeta}_0$  in the expansion for the elevation of the free boundary is obtained in the form

$$\Phi\zeta_0=\zeta^*(\xi,\ \tau)\cos\gamma t_1,$$

where  $\gamma = (\lambda \xi \tanh \xi H)^{1/2}$  and  $\xi^*$  are expressed in terms of the initial data and  $\tau$ .

The functions  $\mathbf{w}_k = (w_{xk}, w_{zk})$ , which occur in the domain D<sub>S</sub>, compensate the discrepancies in the fulfillment of the no-slip conditions in (1) and are determined by means of the second iteration process in [3]. For this purpose we introduce the dilation transformation  $z = -H + \varepsilon s$  and require that  $\mathbf{w}_k$  and their derivatives decrease as  $s \rightarrow \infty$ . Then  $w_{z0} = 0$ ,  $w_{x0}$  are determined from the heat-conduction equation with constant coefficients, and  $w_{z1}$  is obtained in the form

$$L\Phi w_{z_1} = -\lambda \sqrt{\sigma} \xi^2 (\sigma^2 + \gamma^2)^{-1} e^{-s \sqrt{\sigma}} \zeta^* (\xi, \tau).$$

The functions  $\zeta_1$ ,  $\beta_1$ ,  $\omega_1$  in the expansions (2) and (3) are determined by applying the first iteration process to the conditions on the free boundary (z = 0) in Eq. (1). As a result, for  $\varphi_1$  and  $\zeta_1$  we derive the system

$$\frac{\partial \zeta_1}{\partial t_1} + \Pi \zeta_0 = v_{z_1}, \ \frac{\partial \varphi_1}{\partial t_1} + \Pi \varphi_0 + \lambda \zeta_1 = 0 \ (z = 0), |$$

$$\zeta_1 = \varphi_1 = 0 \ (t_1 = 0),$$
(4)

where the operator  $\Pi = \frac{\partial \beta_1}{\partial t} \frac{\partial}{\partial t_1} + \frac{\partial \omega_1}{\partial t} \frac{\partial}{\partial \tau}$ 

Separating the variables  $t_1$  and  $\tau$  in (4), we obtain the function  $\zeta^*$  in the form

$$\zeta^*(\xi,\tau) = \Phi \zeta_* e^\tau. \tag{5}$$

Now, eliminating  $\varphi_1$  from the system (4), we obtain the equation for  $\zeta_1$ 

$$\frac{\partial^2 \Phi \zeta_1}{\partial t_1^2} + \gamma^2 \Phi \zeta_1 = \left[ \frac{\lambda \xi^2 \sqrt{2}}{\sqrt{\gamma} \operatorname{ch}^2(\xi H)} M(\gamma t_1) + 2 \frac{\partial \beta_1}{\partial t} \cos \gamma t_1 + 2 \frac{\partial \omega_1}{\partial t} \gamma^{-1} \sin \gamma t_1 \right] \zeta^*, \tag{6}$$

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$$M(x) = \cos x \cdot c_1(\sqrt{x}) + \sin x \cdot s_1(\sqrt{x}); \ c_1(x) = \sqrt{\frac{2}{\pi}} \int_0^x \cos \xi^2 d\xi; \ s_1(x) = \sqrt{\frac{2}{\pi}} \int_0^x \sin \xi^2 d\xi.$$

From (6) we deduce  $\zeta_1$ . According to the multiple-scale method [4], the unknown functions  $\omega_1$  and  $\beta_1$  are determined from the condition that the coefficients of  $\varepsilon_1$  in the asymptotic expansions (2) are bounded as  $t \to \infty$ ; as a result, we have

$$\beta_1 = \beta t, \ \omega_1 = \gamma \beta t, \ \beta = -\lambda \xi^2 / [2\sqrt{2\gamma^2}\sqrt{\gamma} \operatorname{ch}^2(\xi H)].$$

For the first two terms of the asymptotic expansion of the elevation of the free surface  $\zeta$  we have

$$\zeta \sim \zeta_{0} + \varepsilon \zeta_{1}, \ \Phi \zeta_{0} = \cos \gamma \left(1 + \varepsilon \beta\right) t \cdot \Phi \zeta_{*} e^{-\varepsilon \gamma \beta t},$$

$$\Phi \zeta_{1} = \frac{\lambda \xi^{2}}{2 \sqrt{2} \gamma^{2} \sqrt{\gamma} \operatorname{ch}^{2}(\xi H)} \left[ \gamma t \left(\cos \gamma t - \sin \gamma t\right) - \sqrt{\frac{2\gamma t}{\pi}} + M\left(\gamma t\right) + 2\gamma t \left(c_{1}\left(\sqrt{\gamma t}\right) \sin \gamma t - s_{1}\left(\sqrt{\gamma t}\right) \cos \gamma t\right) \right] \Phi \zeta_{*} e^{-\varepsilon \gamma \beta t}.$$
(7)

We consider the case of a liquid of infinite depth. Now the last condition in the system (1) is satisfied for  $z = -\infty$ , and the coefficients  $w_k$  and  $r_k$  are absent in the expansions (2). The expression for the elevation  $\zeta_0$  of the free boundary of an ideal fluid is obtained in the form  $\Phi \zeta_0 = \cos \varphi t_1 \cdot \zeta^*(\xi, \tau)$ , where  $\varphi = (\lambda | \xi |)^{1/2}$ and  $\zeta^*$  is determined according to (5).

As  $\varepsilon \to 0$  a boundary layer is formed only near the free boundary  $\Gamma$ . The functions  $\mathbf{h}_k = (\mathbf{h}_{\mathbf{x}k}, \mathbf{h}_{\mathbf{z}k})$  compensate the discrepancy in the fulfillment of the dynamic condition for the tangential stress on  $\Gamma$  and are determined by the second iteration process, where  $\mathbf{h}_0 = \mathbf{h}_{\mathbf{z}\mathbf{1}} = \mathbf{q}_k = 0$  ( $k \ge 0$ ):  $\mathbf{L}\Phi\mathbf{h}_{\mathbf{z}\mathbf{2}} = -2\lambda \xi^3 (\sigma^2 + \varphi^2)^{-1} \exp(-s\sqrt{\sigma}) \zeta^*$ ,  $s = z/\varepsilon$ . The coefficients  $\beta_2$  and  $\omega_2$  in the expansions (3) are calculated concurrently with the determination of the functions  $\mathbf{v}_2$ ,  $\zeta_2$ ,  $\mathbf{p}_2$ . We note that in the given situation  $\mathbf{v}_1 = \mathbf{p}_1 = \zeta_1 = \omega_1 = \beta_1 = 0$ , and  $\zeta_2$  is determined from the equation

$$\Phi \zeta_{\mathfrak{g}} = \left[ \left( \varphi \beta_{\mathfrak{g}} + 2\xi^{2} \varphi^{-1} \right) \sin \varphi t_{\mathfrak{g}} - \left( \omega_{\mathfrak{g}} + 2\xi^{2} t_{\mathfrak{g}} \right) \cos \varphi t_{\mathfrak{g}} \right] e^{\tau} \Phi \zeta_{\mathfrak{g}}.$$

From the condition of boundedness of the coefficients of  $\varepsilon^2$  in the expansions (2) as  $t \to \infty$  we deduce expressions for  $\beta_2$  and  $\omega_2$ :  $\omega_2 = -2\xi^2 t$ ,  $\beta_2 = 0$ .

For the asymptotic expansion of the elevation of the free boundary, up to terms of order  $\varepsilon^3$ , we obtain

$$\zeta = \int_{-\infty}^{\infty} e^{-2\varepsilon^2 \xi^2 t} \Phi \zeta_* \left( \cos \varphi t + 2\varepsilon^2 \xi^2 \varphi^{-1} \sin \varphi t \right) e^{i\xi x} d\xi + O(\varepsilon^3).$$
(8)

The constructed asymptotic expansions (2) and expressions (7) and (8) describe the attenuation of the waves generated by the initial disturbance of the free surface at times of the order  $O[(\text{Re})^{1/2}]$  and O(Re), respectively. We note that the coefficient of  $\varepsilon^0$  in the asymptotic formulas (8) coincides with the well-known integral of Sretenskii [1], and upon expansion of the exponential function  $\exp(-2\varepsilon^2\xi^2t)$  into a power series in  $\varepsilon$  the first two terms of the asymptotic representation of  $\zeta$  in [2] are obtained.

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